

The SR1H is part of a series of rugged, lowcost, easy to install high performance string pots built for wet environments and outdoor applications.

The SR1H comes in two ranges: 0-125 inches and 0-175 inches and is the perfect low-cost CANOpen solution indoor factory enviroments or outdoor applications. Every unit ships with a handy mounting bracket giving the user the ultimate flexibility to easily orient the measuring cable to one of four different directions.

## Ordering Information:



## Order No.

## SR1H-125

- 125-inch stroke range - CAN Open Communication
- 5-pin M12 field installable mating plug
- mounting bracket



## Order No

## SR1H-175

175-inch stroke range

- CAN Open Communication
- 5-pin M12 field installable mating plug - mounting bracket


## Order No.

## 9036810-0030

for short-run connections, optional $16-\mathrm{ft}(5 \mathrm{~m})$ long cordset with 5 -pin M12 mating plug.

## SR1H <br> Cable Actuated Sensor <br> Industrial • CANOpen Output Signal

Two Available Stroke Ranges: 0-125 in \& 0-175 in.
Rugged Polycarbonate Enclosure • Simple Installation
Designed for Outdoor \& IP67 environments IN STOCK FOR QUICK DELIVERY!

## Specifications

Repeatability
Resolution
Input Voltage
Input Current

Sensor
Cycle Life
Enclosure
Measuring Cable Weight

Device Type
Vendor ID
Node ID

Data Rate
Error Control
PDO

PDO Modes
SDO
Position Data
Cam Switches
EDS File**

Full Stroke Range, SR1H-125
Full Stroke Range, SR1H-175

Maximum Velocity
Maximum Acceleration
Measuring Cable Tension

Electrical Connection
Environmental Suitability Operating Temperature

## CANOpen Specifications

Communication Profile

Baud Rate Options
125 inches ( 3175 mm ), maximum
175 inches ( 4445 mm ), maximum
.05\% FS.
12-bit
10-36 VDC
100 mA , max.
80 inches (2 meters) per second
10 g (retraction)
23 oz. (6,4 N) $\pm 30 \%$
plastic-hybrid precision potentiometer
250,000 (potentiometer)
polycarbonate
.031-inch dia. bare stainless rope
M12 Connector (mating plug included)
NEMA 6, IP67
$-40^{\circ}$ to $185^{\circ} \mathrm{F}\left(-40^{\circ}\right.$ to $\left.85^{\circ} \mathrm{C}\right)$
2.5 lbs . (1.3 Kg)

CiA 301 V 4.0.2, CANopen Slave
CiA 406 V3.2, Encoder
Company x0002E0, Dept x00
1-127 Adjustable via dipswitch or LSS,
(default set to 1)
125K (default), 250K, 500K, 1M
50ms (default)
Heartbeat, Emergency Message
2 TxPDO, 0 RxPDO, no linking, static mapping
Event / Time triggered, Synch / Asynch
1 server, 0 client
Object Dictionary 6004
Not Supported
contact factory
**-objects 1018, 1A03, 2002, and 6804 in EDS file are not supported

## Position Data Overview



## Electrical Connection

| output <br> signal | connector <br> pin | colorcode <br> (cordset) |
| :---: | :---: | :---: |
| $\mathrm{n} / \mathrm{c}$ | 1 | brown |
| $10 \ldots 36 \mathrm{VDC}$ | 2 | white |
| common | 3 | blue |
| CAN high | 4 | black |
| CAN low | 5 | green/yellow |



16 ft . Cordset (optional)


Internal Controller Board


LSS, Baud Rate, Node ID Settings and Status LED
located on controller board

LSS, Baud Rate and Node ID settings:
LSS, Baud Rate and Node ID settings are set via dip switch found on the internal controller board. To gain access to the controller board, remove the 4 cover attaching screws and carefully separate the sensor cover from the main body.

Follow the instructions on the following pages for desired settings and reinstall sensor cover.

## Status LED - Indicates Operating Condition of the Potentiometer

| green <br> on <br> off <br> off | flash |  |
| :---: | :---: | :--- |
| emergency message (high) |  |  |
| on | off | buffer (high) |
| flash | off | buffer (low) |
| flash | on | emergency message (low) |

## Settings:

|  | LSS settings | SW1 |
| :---: | :---: | :---: |
|  | disabled | off |
| options | enabled | on |

## LSS Settings:

IF DIP Switch 1 is set to "on" position, then LSS will be functional and uses the contents of EEPROM including Node ID and Baud Rate. If DIP Switch 1 is set to "off" position, then DIP switches will override information in EEPROM including the Node ID and Baud Rate.

## BAUD Rate:

If DIP Switch 1 is set to "off" then BAUD rate is set via DIP switch 2 and 3 as shown :
transmission
rate
options $\left\{\begin{array}{c|cc}\text { baud rate } & \text { SW2 } & \text { SW3 } \\ \hline 125 \mathrm{kbps} & \text { off } & \text { off } \\ 250 \mathrm{kbps} & \text { on } & \text { off } \\ 500 \mathrm{kbps} & \text { off } & \text { on } \\ 1 \mathrm{Mbps} & \text { on } & \text { on }\end{array}\right.$


## Manufacturer Objects:

| Index | Sub-Index | Name | Default | Comment |
| :--- | :--- | :--- | :--- | :--- |
| 2000 |  | Raw Position Value |  | This is the averaged, non-scaled value from the encoder. |

## Device Profile Area:

| Index | Sub-Index | Name | Default | Comment |
| :---: | :---: | :---: | :---: | :---: |
| 6000 |  | Operating Parameters | 0X0000 |  |
| 6004 |  | Position Value |  | Counts proportional to measuring cable extension. Nominal values are $0 \times 006$ with cable fully retracted and $0 \times F E 5$ with cable fully extended. Format of data in CAN message is little endian - least significant byte pair first. Therefore 0x008 would be shown as " 0800 " and $0 \times F E 5$ would be shown as "E5 0 F" |
| 6400 |  | Area State Register |  | SubNumber $=2$ (indicates underflow or overflow per CiA406) |
|  | 0 | Highest Subindex | $0 \times 01$ |  |
|  | 1 | Work Area State Channel 1 | 0 |  |

## Device Profile Area (cont.):

| Index | Sub-Index | Name | Default | Comment |
| :---: | :---: | :---: | :---: | :---: |
| 6401 |  | Work Area Low Limit |  | The averaged, non-scaled (raw) encoder data below which the encoder is out of range. |
|  | 0 | Highest Subindex | 0x01 |  |
|  | 1 | Work Area Low Limit Channel1 | 0x024 |  |
| 6402 |  | Work Area High Limit |  | The averaged, non-scaled (raw) encoder data above which the encoder is out of range. |
|  | 0 | Highest Subindex | 0x01 |  |
|  | 1 | Work Area High Limit Channel 1 | 0xF4E |  |
| 6500 |  | Operating Status | 0x0000 |  |
| 6501 |  | Measuring Step | 1 | Position Measuring Step. Can be set by user to convert Position Value (Object 6004) to measurement units (inches, mm). Default is set to 1 . |

## Communication Area Profile:

| Index | Sub-Index | Name | Default | Comment |
| :---: | :---: | :---: | :---: | :---: |
| 1000 |  | Device Type | $0 \times 00080196$ | Device Profile 406 |
| 1001 |  | Error Register | 0 | Manufacturer Specific Error bit 7 is set when sensor is outside of calibrated range and cleared when back in range. |
| 1003 |  | Pre-Defined Error Field |  | SubNumber $=9$ (lists last eight Emergency Messages) |
|  | 0 | Number of Errors | 0 |  |
|  | 1 | Standard Error Field 1 |  |  |
|  | 2 | Standard Error Field 2 |  |  |
|  | 3 | Standard Error Field 3 |  |  |
|  | 4 | Standard Error Field 4 |  |  |
|  | 5 | Standard Error Field 5 |  |  |
|  | 6 | Standard Error Field 6 |  |  |
|  | 7 | Standard Error Field 7 |  |  |
|  | 8 | Standard Error Field 8 |  |  |
| 1005 |  | SYNC COB-ID | 0x80 |  |
| 1010 |  | Store Parameters |  | SubNumber=2 |
| 1010 | 0 | Highest Subindex | 0x01 | Only "Save All Parameters" feature supported |
|  | 1 | Save All Parameters |  | Write "save" or "evsa" to save parameters to EEPROM. They are automatically loaded on power up/reset. Saves the value of all R/W object dictionary entries. |
| 1014 |  | Emergency COB-ID | $\begin{aligned} & \text { \$NodeID + } \\ & 0 \times 80 \end{aligned}$ | COB-ID Emergency Message |
| 1015 |  | Emergency Inhibit Time | 0 | Multiple of $100 \mu \mathrm{~s}$. Minimum time between transmissions of emergency messages. |
| 1017 |  | Producer Heartbeat Time | 0 | Multiples of 1 ms . Time between transmission of heartbeat messages. $0=$ disabled |

## Communication Area Profile (cont.):

| Index | Sub-Index | Name | Default | Comment |
| :---: | :---: | :---: | :---: | :---: |
| 1018 |  | Identity Object |  |  |
|  | 0 | Number of Entries | 4 |  |
|  | 1 | Vendor Id | 0x2E0 |  |
|  | 2 | Product Code | 269 (decimal) | Celesco Reference \#604269 |
|  | 3 | Revision Number | 2 |  |
|  | 4 | Serial Number | 0x00000000 |  |
| 1800 |  | Tx PDO Comm. Parameter |  | PDO1 |
|  | 0 | Number of Entries | 5 |  |
|  | 1 | COB-ID | $\begin{aligned} & \text { \$NodeID + } \\ & 0 \times 108 \end{aligned}$ | COB-ID used by PDO1 |
|  | 2 | Transmission Type | 254 (decimal) | PDO1 Tx Type: $0=$ on Sync Message. 254 = Asynchronous Tx |
|  | 3 | Inhibit Time | 0 | Multiple of $100 \mu \mathrm{~s}$. Minimum time between transmissions of the PDO |
|  | 5 | Event Timer | 0x32 | If non-zero then transmits the PDO periodically. This value is a multiple of 1 ms . |
| 1801 |  | Tx PDO Comm. Parameter |  | PDO2 |
|  | 0 | Number of Entries | 5 |  |
|  | 1 | COB-ID | $\begin{aligned} & \text { \$NodeID + } \\ & 0 \times 280 \end{aligned}$ | COB-ID used by PDO2 |
|  | 2 | Transmission Type | $0 \times 01$ | PDO2 Tx Type: $0=$ on Sync Message. $254=$ Asynchronous Tx |
|  | 3 | Inhibit Time | 0 | Multiple of $100 \mu \mathrm{~s}$. Minimum time between transmissions of the PDO |
|  | 5 | Event Timer | 0 | If non-zero then transmits the PDO periodically. This value is a multiple of 1 ms . |
| 1 A 00 |  | Tx PDO Mapping Parameter |  | Subnumber = 2 |
|  | 0 | Number of Entries | 1 |  |
|  | 1 | PDO Mapping Entry | 0x60040020 | Mapping Parameter |
| 1A01 |  | Tx PDO Mapping Parameter |  | Subnumber = 2 |
|  | 0 | Number of Entries | 1 |  |
|  | 1 | PDO Mapping Entry | 0x60040020 | Mapping Parameter |

## Changing the Cable Exit

## Changing Measuring Cable Exit

To change the direction of the measuring cable, remove the 4 mounting bracket screws and rotate bracket to one of four available positions. See figures 1-4 on the following pages for mounting dimensions.

## Changing Electrical Connector Direction

To change the position of the electrical connector, remove the 4 rear cover screws and carefully separate rear cover from the sensor body.
Rotate the rear cover to desired position being careful to not tangle the wiring harness that runs to the connector.

## Cable Exit Direction Options



Mounting Bracket


see fig. 2
see fig. 3


Electrical Connector

see fig. 4

Fig. 1 - Outline Drawing (as shipped)

units are in inches [mm] tolerances are $\pm .04[1,0]$ unless otherwise noted

Fig. 2-"Up" Cable Exit Direction


Fig. 3 - "Down" Cable Exit Direction


Fig. 4 - "Rear" Cable Exit Direction


| Model | $A$ | $B$ |
| :---: | :---: | :---: |
| 125 -inch | $2.00 \pm .13$ | $2.37 \pm .13$ |
|  | $[50,8 \pm 3,3]$ | $[60,22 \pm 3,3]$ |
| 175 -inch | $2.87 \pm .13$ | $3.24 \pm .13$ |
|  | $[72,8 \pm 3,2]$ | $[82.2 \pm 3,2]$ |


units are in inches [mm] tolerances are $\pm .04[1,0]$ unless otherwise noted

NORTH AMERICA
Measurement Specialties, Inc. a TE Connectivity Company

20630 Plummer Street
Chatsworth, CA 91311
Tel +1-800-423-5483
Tel +1-818-701-2750
Fax +1-800-701-2799
customercare.chtw@te.com

## te.com/sensorsolutions

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